# Frame Bounds for Gabor Frames in UCLA **Finite Dimensions**

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**Abstract:** One of the key advantages of a frame is its redundancy. Provided we have a control on the frame bounds, this redundancy allows to achieve robust reconstruction of a signal from its frame coefficients that are corrupted by noise, rounding error, or erasures. We discuss Gabor frames  $(q, \Lambda)$  with generic frame set  $\Lambda$  and random window q and show that, with high probability, such frames have frame bounds similar to the frame bounds of randomly generated frames with independent frame vectors.

#### Introduction

A finite set of vectors  $\Phi = \{\varphi_j\}_{j=1}^N \subset \mathbb{C}^M$  is called a frame with frame bounds  $0 < A \leq B$ if, for any  $x \in \mathbb{C}^M$ ,

$$A||x||_{2}^{2} \leq \sum_{j=1}^{N} |\langle x, \varphi_{j} \rangle|^{2} \leq B||x||_{2}^{2}.$$

We identify a frame  $\Phi$  with its synthesis matrix  $\Phi$ , having the frame vectors  $\varphi_i$  as its columns. Its adjoint  $\Phi^*$  is called the analysis matrix of the frame  $\Phi$ .

# Idea of the proof

Let  $\Lambda$  be a general subset of  $\mathbb{Z}_M \times \mathbb{Z}_M$ . Fix any  $m \in \mathbb{N}$  and consider the matrix  $H = \Phi_{\Lambda} \Phi^*_{\Lambda} - \frac{|\Lambda|}{M} I_M$ . Following the idea of [2], we obtain that  $\mathbb{P}\left\{\frac{|\Lambda|}{M}(1-\delta) \le \sigma_{\min}^2(\Phi_{\Lambda}^*) \le \sigma_{\max}^2(\Phi_{\Lambda}^*) \le \frac{|\Lambda|}{M}(1+\delta)\right\} = \mathbb{P}\left\{||H||_2 \le \frac{|\Lambda|}{M}\delta\right\}$  $= \mathbb{P}\left\{ ||H||_{2}^{2m} > \frac{|\Lambda|^{2m}}{M^{2m}} \delta^{2m} \right\} \leq \frac{M^{2m}}{|\Lambda|^{2m}} \delta^{-2m} \mathbb{E}(||H^{m}||_{2}^{2}) \leq \frac{M^{2m}}{|\Lambda|^{2m}} \delta^{-2m} \mathbb{E}(\operatorname{Tr} H^{2m}).$ 

One can further show that [4]



where

$$E_{j_{1}...j_{m}} = \begin{cases} \frac{1}{M_{\alpha}^{m}} \text{, if } \exists \alpha \in S_{m} \text{, s.t. } j_{t} - k_{t} = j_{\alpha(t)} - k_{\alpha(t)-1} \text{, } \forall t \in \{1, ..., m\}; \end{cases}$$

The optimal lower and upper frame bounds are given by

$$A = \min_{x \in \mathbb{S}^{M-1}} \sum_{j=1}^{N} |\langle x, \varphi_j \rangle|^2 = \sigma_{\min}^2(\Phi^*), \quad B = \max_{x \in \mathbb{S}^{M-1}} \sum_{j=1}^{N} |\langle x, \varphi_j \rangle|^2 = \sigma_{\max}^2(\Phi^*).$$

**Problem:** Given noisy measurements  $c = \Phi^* x + \delta \in \mathbb{C}^N$ , reconstruct x.

We construct an estimate of x using standard dual frame:

$$\tilde{x} = (\Phi \Phi^*)^{-1} \Phi c = x + (\Phi \Phi^*)^{-1} \Phi \delta.$$

Then the reconstruction error is

$$||\tilde{x} - x||_2^2 \le ||(\Phi\Phi^*)^{-1}\Phi||_2^2 ||\delta||_2^2 = \frac{||\delta||_2^2}{\sigma_{\min}^2(\Phi^*)}.$$

Moreover,

 $\frac{||\tilde{x} - x||_2}{||x||_2} \le \frac{\operatorname{Cond}(\Phi^*)}{\operatorname{SNR}},$ where,  $\operatorname{Cond}(\Phi^*) = \frac{\sigma_{\max}(\Phi^*)}{\sigma_{\min}(\Phi^*)} = \frac{\sqrt{B}}{\sqrt{A}}$  is the condition number of  $\Phi$ , and  $\operatorname{SNR} = \frac{||\Phi^*x||_2}{||\delta||_2}$  is the signal to noise ratio.

**Goal:** Bound  $\sigma_{\max}(\Phi^*)$ ,  $\sigma_{\min}(\Phi^*)$  to ensure robust signal reconstruction.

Extreme singular values are sufficiently well-studied for random matrices with independent entries [1], [3]. The case of structured random matrices corresponding to application relevant frames, such as Gabor frames, is not yet fully studied [2].

# Definition of Gabor frames

1 Translation (or time shift) by  $k \in \mathbb{Z}_M$ , is given by  $T_k x = (x(m-k))_{m \in \mathbb{Z}_M}$ .

0, otherwise.

This translates the problem of bounding the singular values into a combinatorial problem.

### Numerical results

- Steinhaus window g, that is,  $g(m) = \frac{1}{\sqrt{M}}e^{2\pi i y_m}$  and  $y_m \sim \text{i.i.d. Unif}[0,1)$ .
- $\Lambda$  is chosen at random as described in Theorem 2, with  $\tau = \frac{C}{M}$ .



Figure 1 – Left: the dependence of the extreme singular values of the analysis matrix  $\Phi^*_{\Lambda}$  of a Gabor frame  $(g,\Lambda)$  on the ambient dimension M; **Right:** the distribution of the singular values of  $\Phi^*_{\Lambda}$  for the dimensions M = 100, 150, 200, 250, 300.

- O Modulation (or frequency shift) by  $\ell \in \mathbb{Z}_M$  is given by  $M_\ell x = (e^{2\pi i \ell m/M} x(m))_{m \in \mathbb{Z}_M}$ .
- The superposition  $\pi(k,\ell) = M_{\ell}T_k$  of translation by k and modulation by  $\ell$  is a time-frequency shift operator.
- For  $g \in \mathbb{C}^M \setminus \{0\}$  and  $\Lambda \subset \mathbb{Z}_M \times \mathbb{Z}_M$ , the set of vectors

 $(g,\Lambda) = \{\pi(k,\ell)g\}_{(k,\ell)\in\Lambda}$ 

is called the Gabor system generated by the window g and the set  $\Lambda$ . A Gabor system which spans  $\mathbb{C}^M$  is a frame and is referred to as a Gabor frame.

# Main results [4]

We show that for any  $\epsilon \in (0,1)$ , a generic subframe  $(g,\Lambda)$  of  $(g,\mathbb{Z}_M\times\mathbb{Z}_M)$  with  $|\Lambda| = O(M^{1+\epsilon} \log M)$  is has a well-conditioned analysis matrix with high probability.

#### More precisely, for structured $\Lambda$ we have

**Proposition 1.** Let  $(g, \Lambda)$  be a Gabor system with  $\Lambda = F \times \mathbb{Z}_M$ ,  $F \subset \mathbb{Z}_M$ ,  $F \neq \emptyset$ , and  $g \in \mathbb{C}^M$ . Then  $(g, \Lambda)$  is a frame if and only if  $\min_{m \in \mathbb{Z}_M} \{ ||g_{F_m}||_2 \} \neq 0$ , where  $g_{F_m}$  is the restriction of g to the set of coefficients  $F_m = \{m - k\}_{k \in F} \subset \mathbb{Z}_M$ . Moreover, in this case the optimal lower and upper frame bounds for  $(g, \Lambda)$  are  $A = M \min_{m \in \mathbb{Z}_M} \{ ||g_{F_m}||_2^2 \}$  and  $B = M \max_{m \in \mathbb{Z}_M} \{ ||g_{F_m}||_2^2 \}$ , respectively.

**Note:** an analogous result is true for the the case when  $\Lambda = \mathbb{Z}_M \times F$ , for some  $F \subset \mathbb{Z}_M$ .

In the case of a generic frame set  $\Lambda$ , we have

**Theorem 2.** Let g be a Steinhaus window and consider a Gabor system  $(g, \Lambda)$ . 1 For any  $\Lambda \subset \mathbb{Z}_M \times \mathbb{Z}_M$  and  $\varepsilon \in (0,1)$ , with probability at least  $1 - \varepsilon$ ,



Figure 2 – The dependence of the numerically estimated trace expectation  $\frac{M^{2m}}{|\Lambda|^{2m}}\delta^{-2m}\mathbb{E}(\operatorname{Tr} H^{2m})$  on the ambient dimension M (horizontal axis) and the parameter C (vertical axis), for a fixed m. Left:  $\Lambda$  is chosen at random, as described in Theorem 2, with  $\tau = \frac{C}{M}$ ; **Right:**  $\Lambda = F \times \{0, 1, \dots, |\frac{M}{2}|\}$ .

The obtained numerical results suggest that

- 1. In the case when random  $\Lambda$  is constructed as in Theorem 2 with  $\tau = \frac{C}{M}$ , there exist constants 0 < k < K not depending on M, such that all the singular values of the analysis matrix  $\Phi^*_{\Lambda}$  are inside the interval  $\left|k\frac{|\Lambda|}{M}, K\frac{|\Lambda|}{M}\right|$  with high probability.
- $\bigcirc$  Even in the worst case scenario choice of  $\Lambda$  normalized trace expectation decreases rapidly with the dimension. This allows to conjecture that Theorem 2 can be further generalized using the proposed method.

#### **Conclusions and Forthcoming Research**

$$\sigma_{\max}^2(\Phi_{\Lambda}^*) \leq \frac{|\Lambda|}{M} + \sqrt{\frac{|\Lambda|}{\varepsilon}} \left(1 - \frac{|\Lambda|}{M^2}\right).$$

2 Let  $\varepsilon \in (0, \frac{1}{2}]$  and C > 0 a sufficiently large constant. Let  $\Lambda \subset \mathbb{Z}_M \times \mathbb{Z}_M$  be a random set, constructed so that  $\mathbf{1}_{\{(k,\ell)\in\Lambda\}} \sim i.i.d$ . Bernoulli $(\tau)$  for all  $(k,\ell) \in \mathbb{Z}_M \times \mathbb{Z}_M$ , where  $au = \frac{C \log M}{M^{1-\varepsilon}}$ . Then, with high probability,



**Note:** the bound in Theorem 2.1 is tight for a full Gabor frame with  $\Lambda = \mathbb{Z}_M \times \mathbb{Z}_M$ . In the case when  $|\Lambda| = \alpha M^2$ , for some  $\alpha \in (0,1)$ , the proven bound gives  $\sigma_{\max}^2(\Phi^*_{\Lambda}) \leq \left(\alpha + \sqrt{\frac{\alpha(1-\alpha)}{\varepsilon}}\right) M$  with probability at least  $1-\varepsilon$ , which is similar to the bound for matrices with independent entries obtained in [1].

While the presented results discuss the case of a generic, randomly generated,  $\Lambda$ , one of the main directions for the future research is to evaluate frame bounds of Gabor frames for all possible frame sets  $\Lambda$  and to investigate their dependencies on the structure of  $\Lambda$ .

# References

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